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Overview

The AO high-level coordination is implemented by three components, called "arbitrators":

- **Overall AO arbitrator** (simply called "AO Arbitrator"): implements the overall AO finite state machine and talks directly with the AOS. To operate the system, gives commands to the two lower-level arbitrators.
- **AdSec arbitrator**: implements the Adaptive Secondary finite state machine
- **WFS arbitrator**: implements the Wavefront Sensor finite state machine

Arbitrators may be written in any language.

An arbitrator exports a series of commands, which can be called by a higher-level arbitrator, by the AOS or by an external process (e.g. calibration procedures). To allow interoperability from different languages, each arbitrator makes available a library which other processes must use to call arbitrator commands. Programs written in different languages must make their own wrapper around this library.

Hereafter a first draft of the AO Arbitrator structure document:

- [arbitrator.pdf](#): AO Arbitrator: architecture and functionalities
- [AoArbitratorFsm](#): AO Arbitrator FSM and use cases

Requirements

See the attachment *Arbitrator-Requirements.pdf* for a detailed requirement analysis.

Adopted solution

A generic **arbitrator framework** is designed as basis for all arbitrator implementations.

A generic **arbitrator interface** is designed to communicate (send commands and alerts) with the generic arbitrator.

Both "modules" uses object-oriented design and implementation (C++) to allow an easy and safe extension:

- The AOArbitrator extends the framework, providing its own set of commands and FSM.
- The AOArbitrator interface extends the generic interface to provide interaction with the AOArbitrator.

Design 0.9

The design V0.9 UML diagram (for Umbrello tool) is available in *CVS/Documentation/Architecture/AO-Arbitrator-Framework_0_9.xmi*.

Design 1.0 (final)

The UML diagram (for Umbrello tool) is available in *CVS/Documentation/Architecture/AO-Arbitrator-*

Framework.xmi.

Please see code in CVS (*lib/arbitrator* and *Arbitrator/aoarbitrator*).

Arbitrator: how to add a new command

Each arbitrator has its own subdirectory in `$ADOPT_SOURCE/lib/arblib` and `$ADOPT_SOURCE/Arbitrator`. The structure is identical apart from name prefixes. Here we will use as an example the main AO Arbitrator (`aoArb`):

AOArbitrator folder's structure:

<code>\$ADOPT_SOURCE/Arbitrator/aoarbitrator</code>	Contains the extension (implementation) for the AO Arbitrator of the framework arbitrator classes.
<code>\$ADOPT_SOURCE/lib/arblib/aoArb/</code>	Contains the definition for the AO Arbitrator of the Arbitrator framework classes.

The **Arbitrator Framework** base classes to be known are (omissing the root folder):

<code>lib/arblib/aoArb/Command.h</code>	Defines a base command class.
<code>arbitrator/aoarbitrator/CommandImpl.h</code>	Defines a base command implementation class.

To add a new command to **AO Arbitrator**, the interesting files and folders are (omissing the root folder):

<code>lib/arblib/aoarbitrator/MainArbitratorOpCodes.h</code>	Defines the "operation code" for every available command.
<code>lib/arblib/aoarbitrator/Commands.h</code>	Contains the available commands classes.
<code>lib/arblib/aoarbitrator/Commands.cpp</code>	Implements some command methods, at least <code>::validateImpl()</code> and optionally <code>::log()</code>
<code>lib/arblib/aoarbitrator/AOCommandsExport.h</code>	Export the available commands for boost serialization.
<code>arbitrator/aoarbitrator/AOCommandsImpl.h</code>	Contains the implementations classes for the available commands.
<code>arbitrator/aoarbitrator/AOCommandsImpl.cpp</code>	Contains the implementations classes for the available commands.
<code>frameworkImpl/AOCommandsImplFactory.h</code>	Bind a Command class (actually its operation code) with the corresponding implementation (CommandImpl class)
<code>arbitrator/aoarbitrator/AOFsm.h</code>	Contains an Enum with the opcode values for the FSM
<code>arbitrator/aoarbitrator/AOFsm.cpp</code>	Implements command execution within the FSM

No other files or directories must be changed.

To defines and implement a new command follows this steps:

- Step 1: defines an operation code (type *OpCode*) in the file `lib/arblib/aoarbitrator/`

MainArbitratorOpCodes.h.

- Step 2: create your *MyCommand* class (deriving from *Command.h*) in the *lib/arblib/aoarbitrator/Commands.h* file:
 - Defines a public constructor with at least the parameter *timeout_ms* (optional, but suggested) and a call to the *Command* class constructor (with the *OpCode* defined in Step 1)
 - Add all needed command parameters to the default constructor.
 - Defines a protected default constructor with no parameters (needed for boost serialization).
 - Defines private fields for needed command parameters.
 - Defines a private *serialize(Archive ar, unsigned int version) method* to serialize the base class and the parameters.
 - Implement all pure virtual method of *Command* class.
- Step 3: update the file *lib/arblib/aoarbitrator/AOCommandsExport.h* to enable the boost serialization for your command.

Now your command is fully defined: can be sent using the *AOArbitratorInterface* and received by *AOArbitrator*. Now you need to define an implementation for the command; otherwise the default EMPTY implementation (*EmptyCommandImpl*) will be used.

- Step 4: create your *MyCommandImpl* class (deriving from *CommandImpl*) in the *arbitrator/aoarbitrator/AOCommandsImpl.h* file.
 - Implement all pure virtual method of the *CommandImpl* class.
- Step 5: update the file *arbitrator/aoarbitrator/AOCommandsImplFactory.h* to bind *MyCommandImpl* with the corresponding *MyCommand* class.
- Step 6: add the command opcode to the Enum in *arbitrator/aoarbitrator/AOFsm.h*
- Step 7: add the command execution to the FSM code in *arbitrator/aoarbitrator/AOFsm.cpp*

Todo

Framework and interface design next updates

- **Framework and AOArbitrator:** check return values and errors (only exceptions, please!) for methods
- **Framework:** review transition method to failure state

Next steps

- **AOArbitrator:** complete the set of *CommandsImpl*.
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- **AdSecArbitrator:** begin!

-- **FabioTosetti** - 09 Jan 2008 -- **MarcoXompero** - 16 Oct 2007 -- **AlfioPuglisi** - 18 Feb 2009

Attachments (2)

[Attach files](#) [Show options](#)



[Arbitrator-Requirements.pdf](#) (723.69K)
Version 2 uploaded by Fabio Tosetti on
19 Nov 2007 - 11:41 ... [more](#)



[arbitrator.pdf](#) (3135.12K)
Version 1 uploaded by Marco Xompero
on 16 Oct 2007 - 09:56

Arbitrator requirements analysis

AO Arbitrator architecture and

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